Embedded Controls and Mechatronics

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Author Information

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Course Details

Description

This is an elective course for undergraduate seniors and graduate students. The course is comprised of both analytical and laboratory components and includes a final project. The course content includes four components: modeling, analysis, contol design, and hardware implementation. Two embedded targets are used for hardware implementation: Arduino development board and Microchip dsPIC. Simulink-based target tools are used for programming these embedded processors.

Original Course Documents

Source file URL

Course Contents

Lectures

- Lecture 01: Introduction
- Lecture 02: Mathematical Models of Dynamic Systems
- Lecture 03: System Identification
- Lecture 04: Simulation Analysis of Nonlinear Systems
- Lecture 05: System Modeling
- Lecture 06: Arduino
- Lecture 07: dsPIC
- Lecture 08: Analysis of Linear Control Systems
- Lecture 09: Lead-Lag Control
- Lecture 10: Linear Quadratic Regulator (LOR) Control
- Lecture 11: Controller Design with SISOTool
- Lecture 12: PID Control
- Lecture 13: Optimization-Based Control
- Lecture 14: Linear Quadratic Gaussian (LQG) Control

Labs

- Arduino
 - o <u>Installation Instructions for Arduino</u>
 - o User Guide for Labs with Arduino

- o Arduino Support Files
- dsPIC
 - o <u>User Guide for Labs with dsPIC</u>
 - o dsPIC Support Files

Handouts

- Guidelines for Controller Designs Using State Space Method
- Moments of Inertia

Tests

Quizzes

- Quiz 1
- Quiz 1 Make-up
- Quiz 2

Exams

- <u>Exam 1</u>
- <u>Exam 2</u>



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